



CSC Conflict Resolution

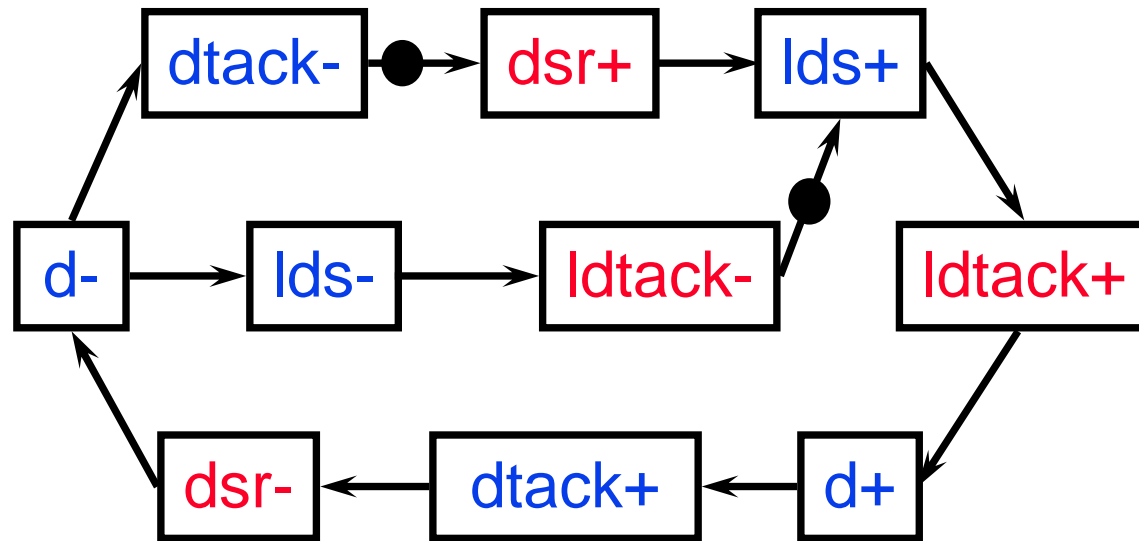
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School of Computing,

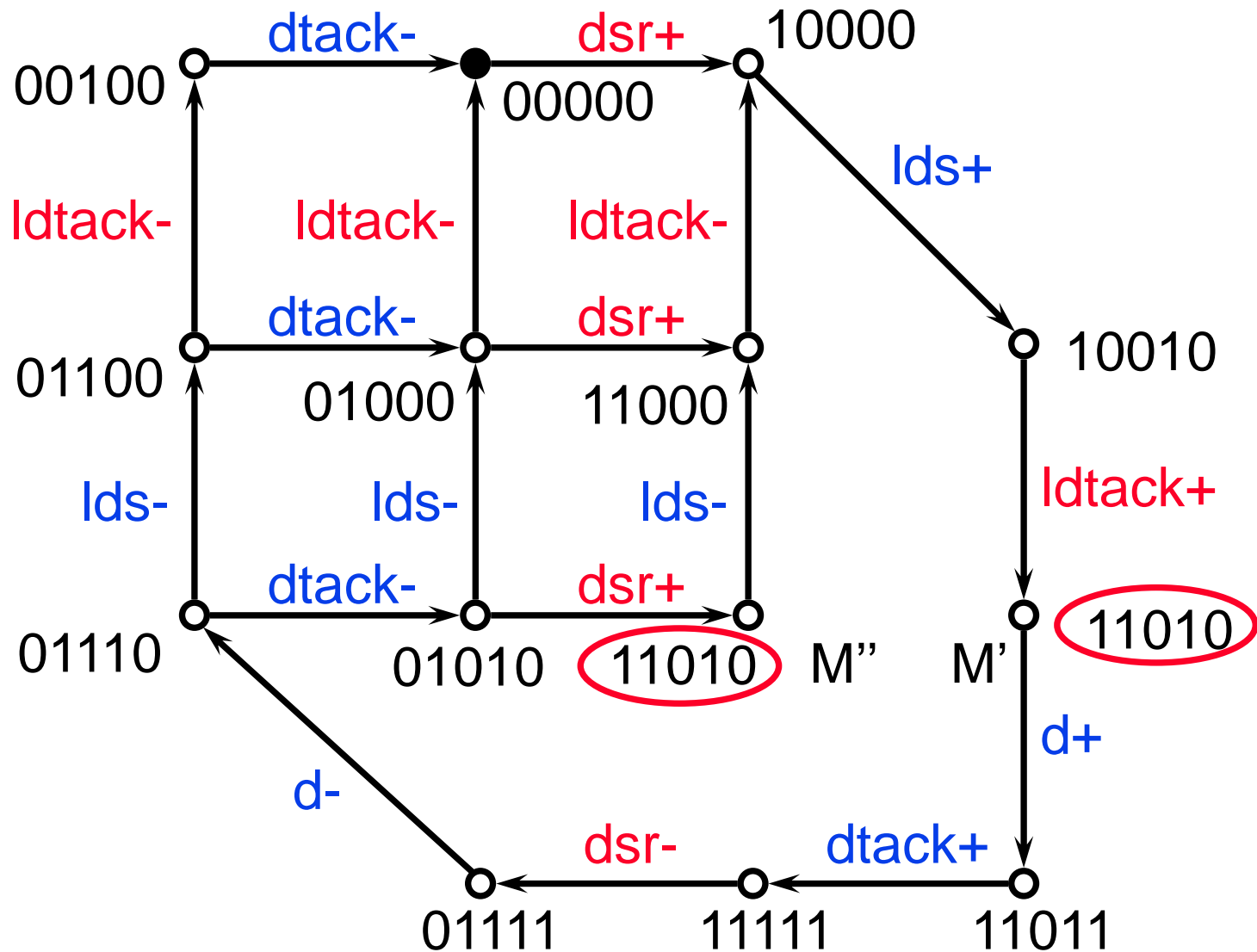
Newcastle University, UK

Online tutorial available from workcraft.org

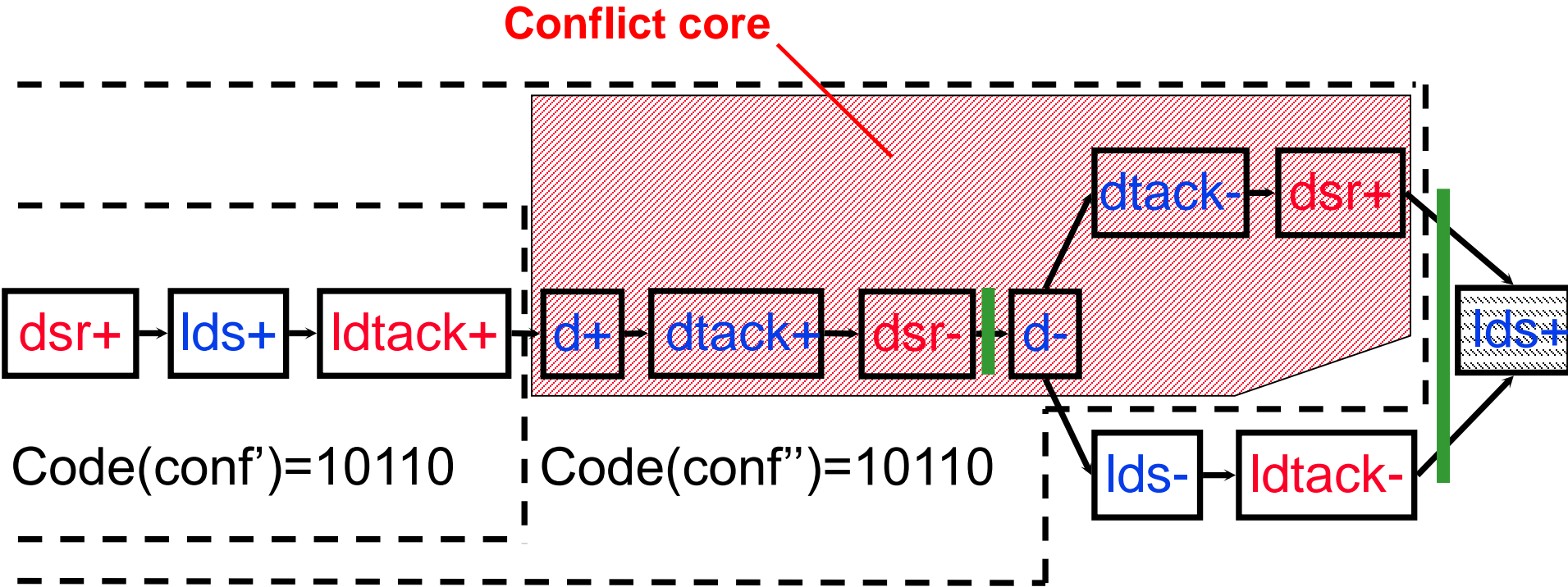
Example: VME Bus Controller



Example: CSC conflict



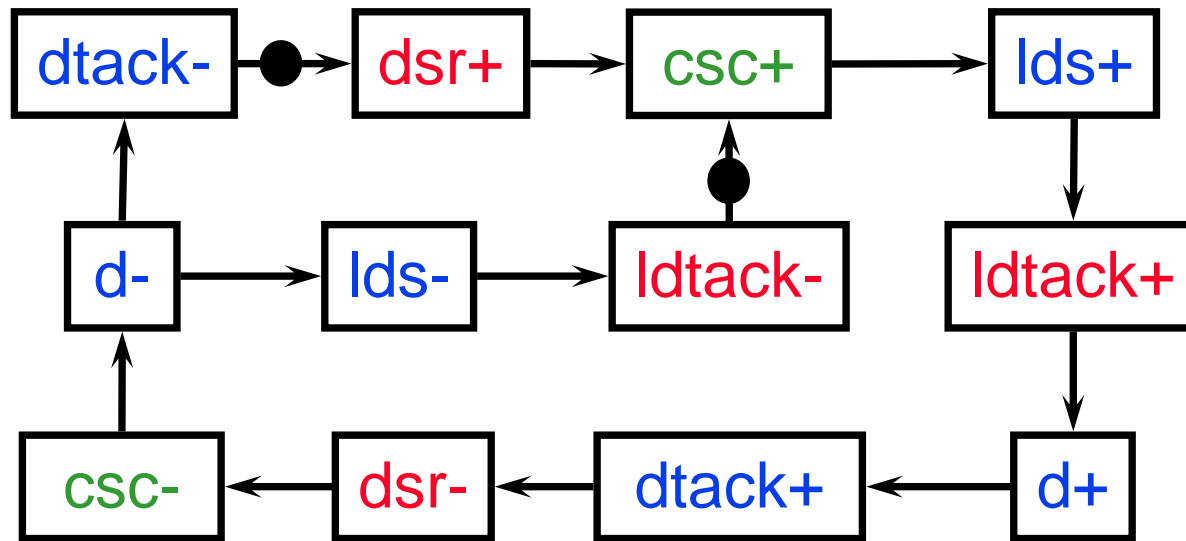
Example: Resolving the conflict



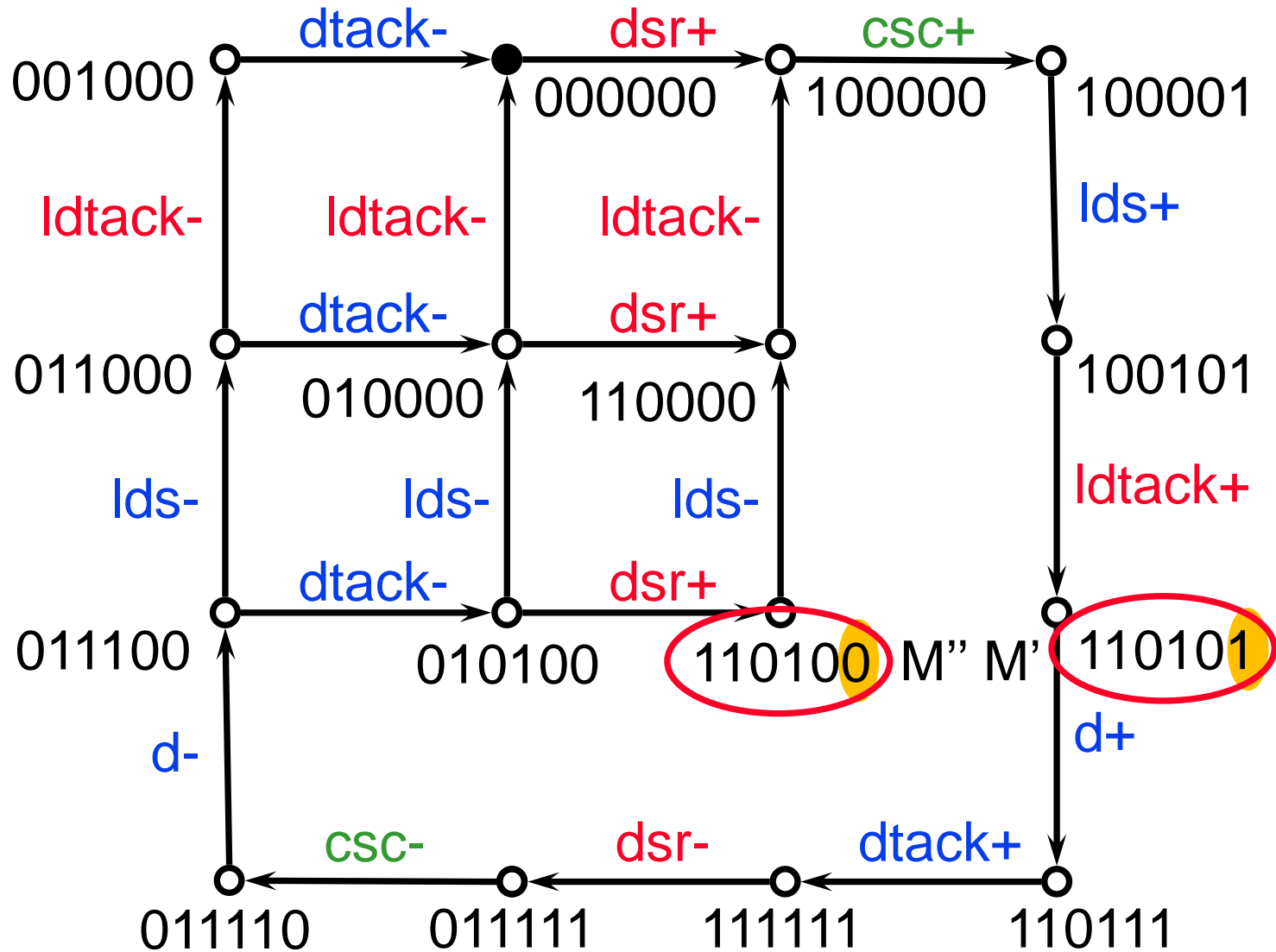
Idea: Insert **csc+** into the core and **csc-** outside the core to break the balance

Note: Cannot delay inputs!

Example: Resolving the conflict

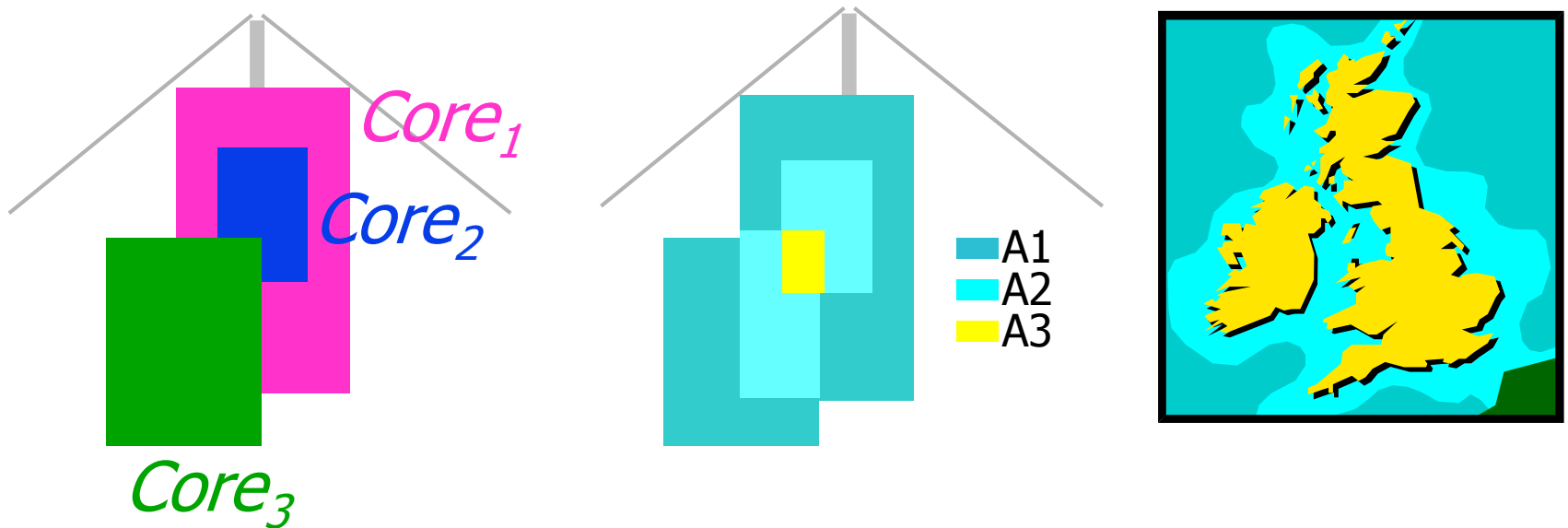


Example: Resolving the conflict

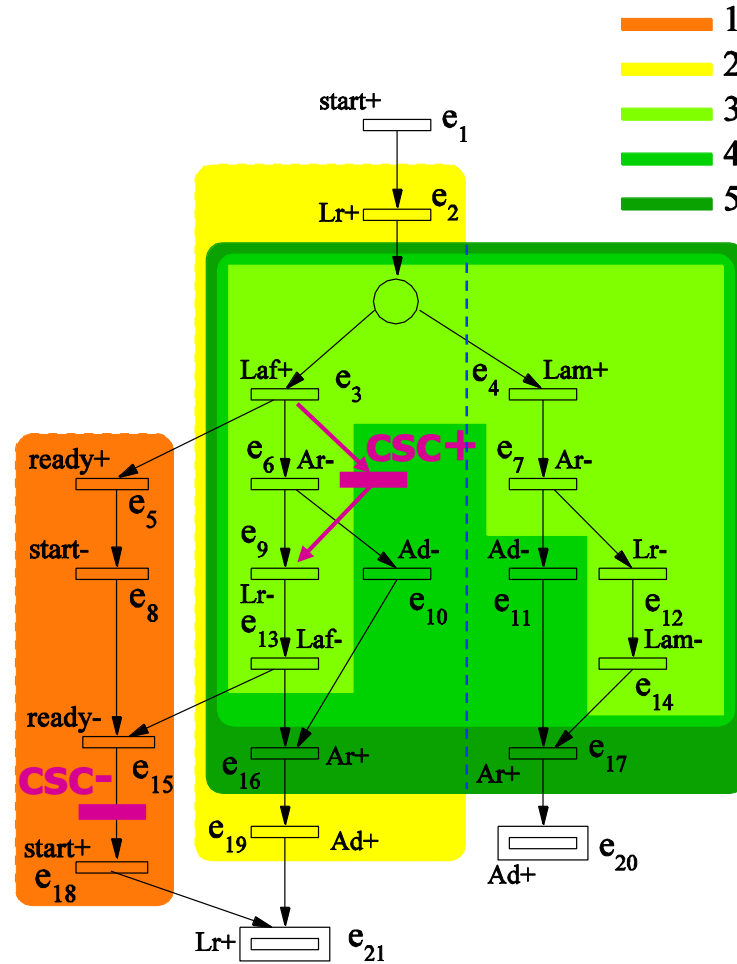


Core map

- Cores often overlap
- High-density areas are good candidates for signal insertion
- Analogy with topographic maps



Example: core map



Concurrency reduction

Introduces a new arc in the STG: $a \rightarrow b$

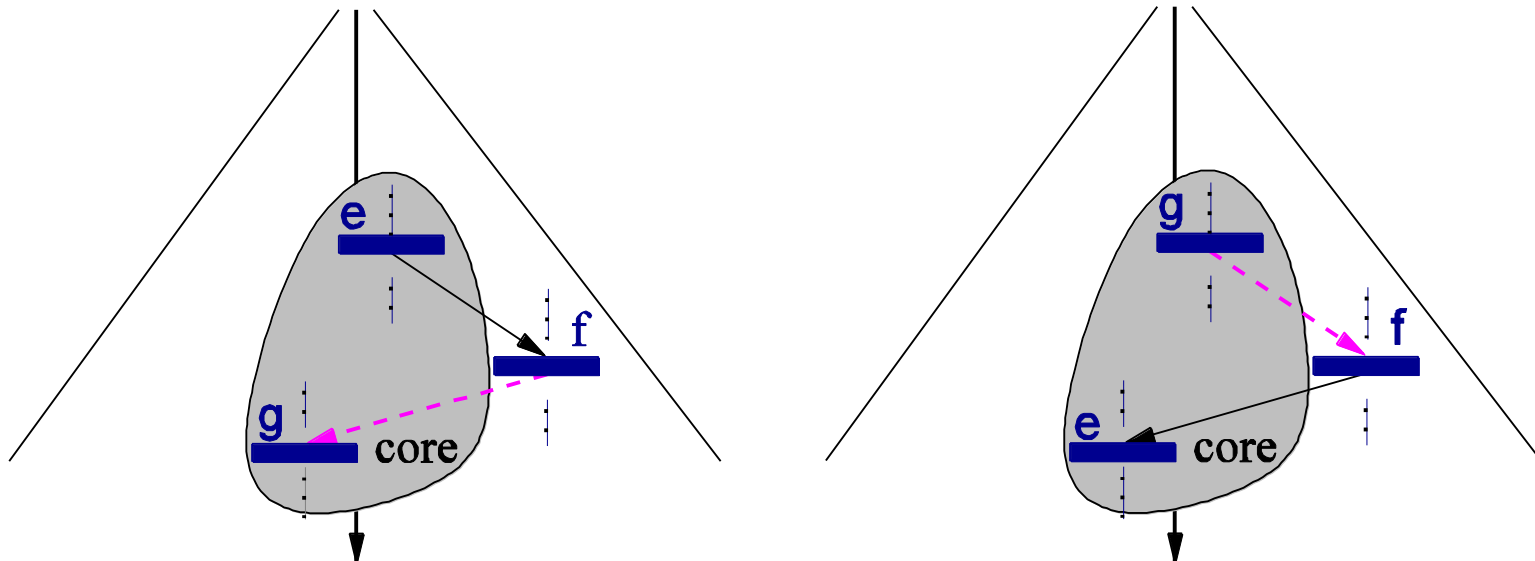
Note: Must not delay inputs, i.e. b cannot be an input!

Note: Changes the behaviour, impacts the environment!

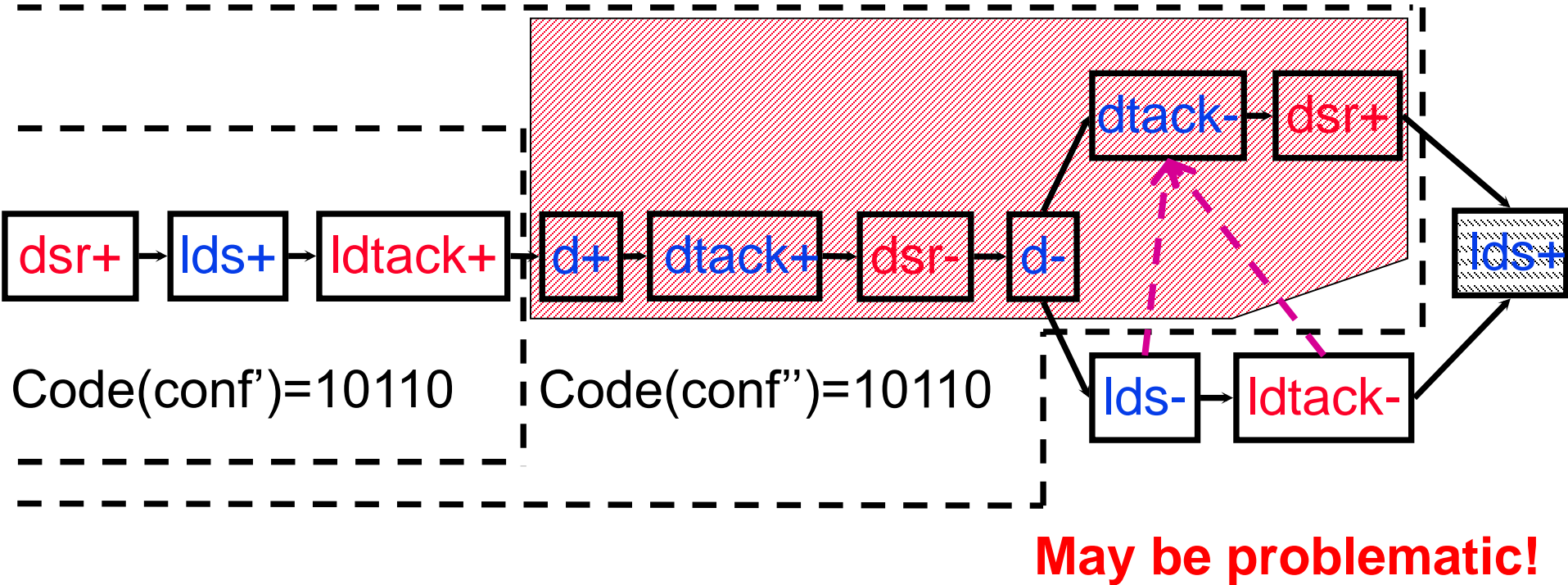
Heuristic: Try not to introduce new triggers of b , e.g. if there is an arc $a^+ \rightarrow b^+$ then $a^- \rightarrow b^-$ is preferred

Used for resolving CSC conflicts and circuit simplification

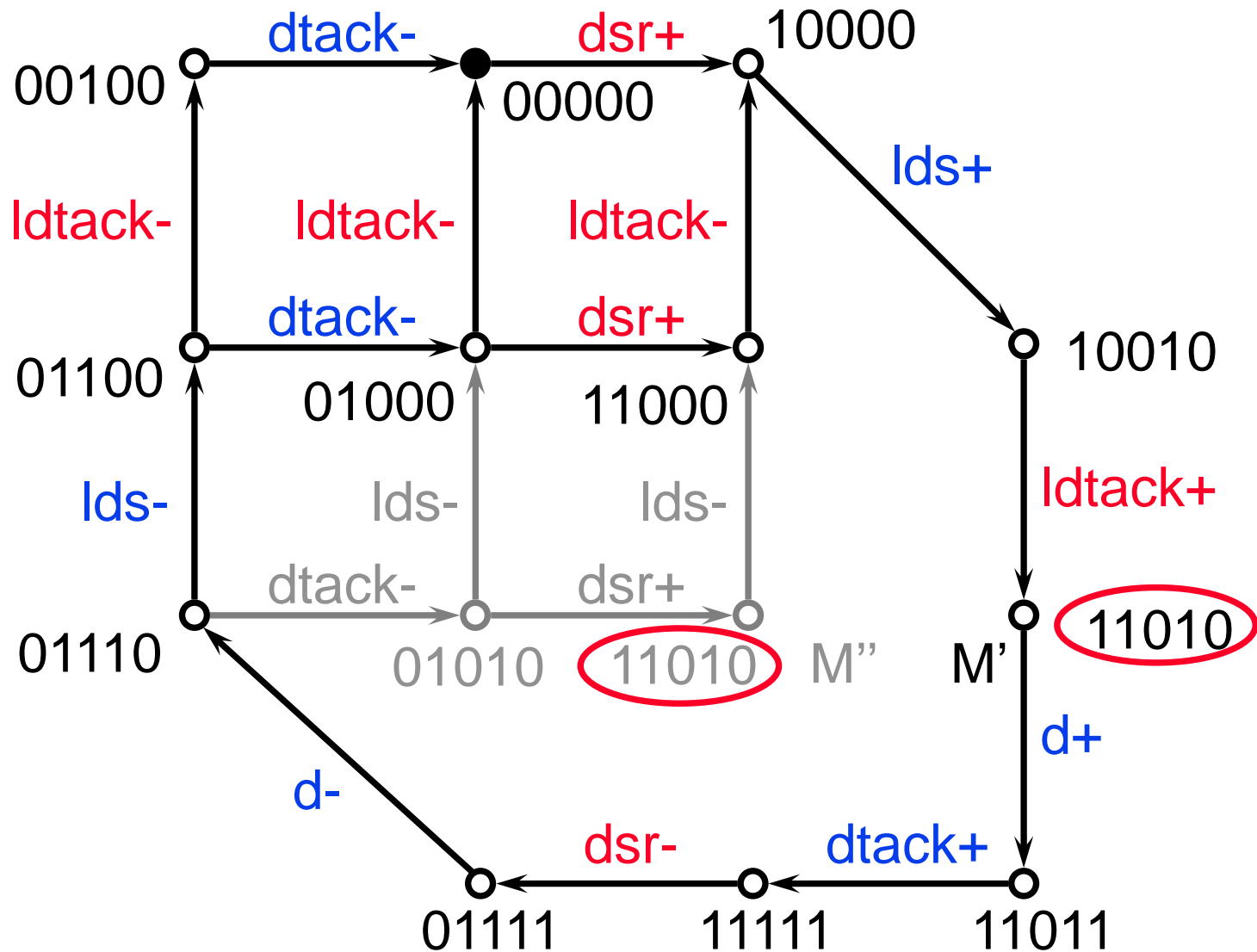
‘Drag’ some events into the core to break the balance:



Example: Resolving the conflict

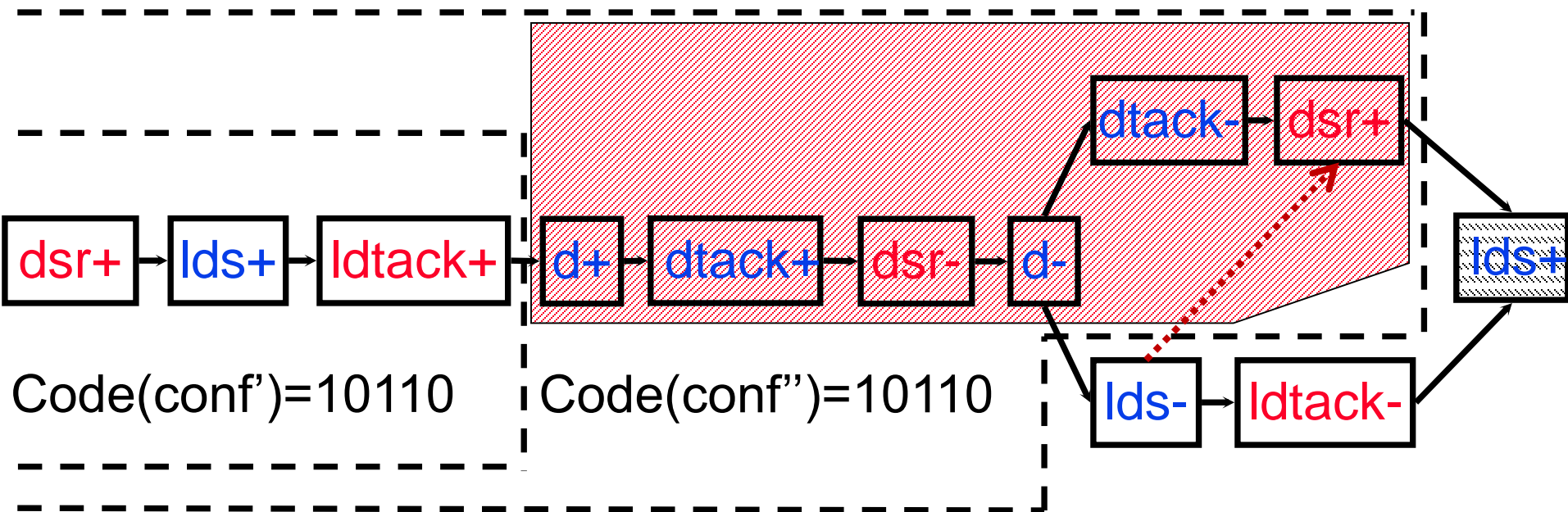


Example: Resolving the conflict

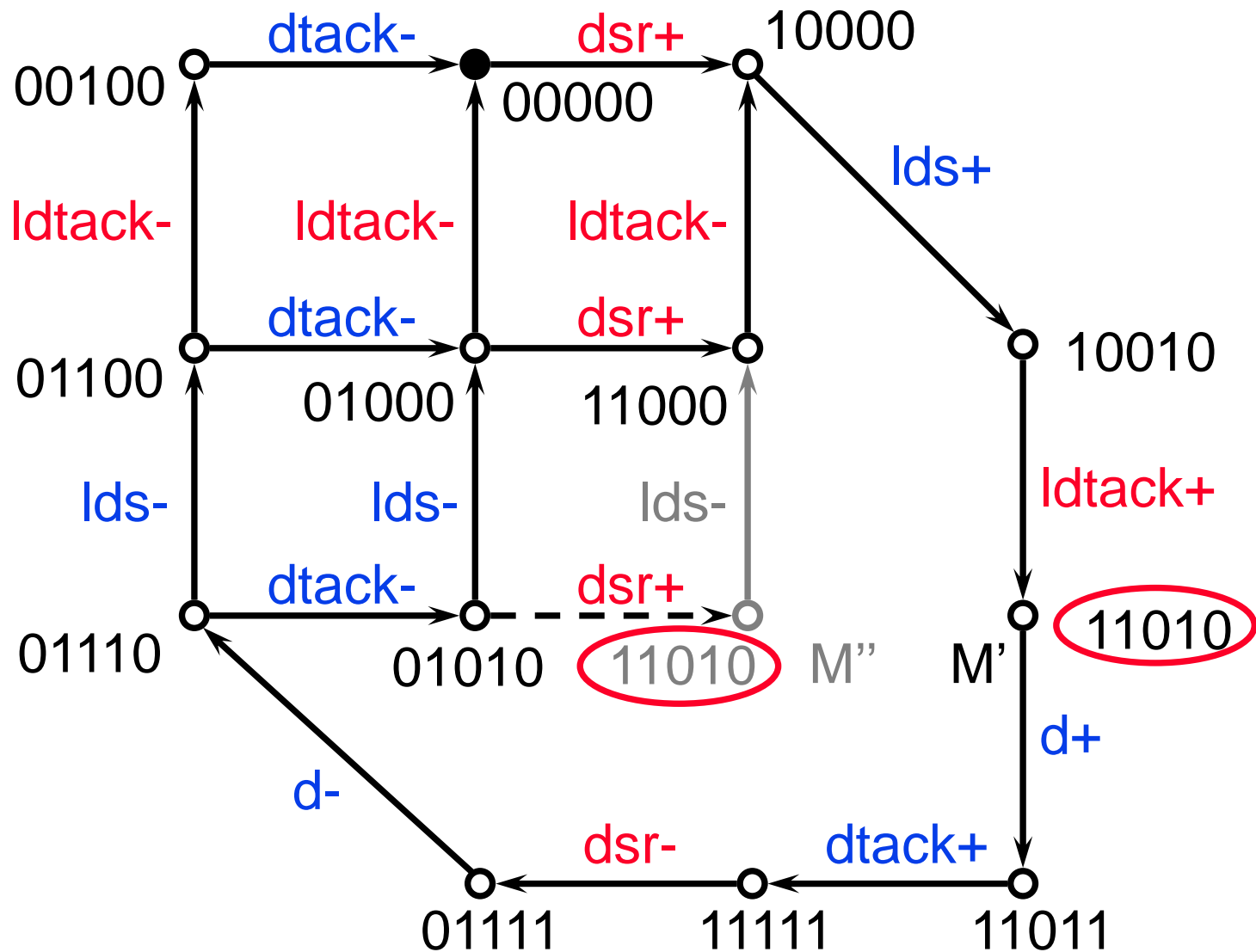


Relative timing assumptions

- “This event will happen faster than that one”
- Break speed-independence, require care & tool support
- Similar to concurrency reductions, but the introduced arcs are special, in particular they don't trigger signals
- Can “delay” inputs



Example: Resolving the conflict



Comparison of the methods

- **Signal insertions – paracetamol**
 - 😊 behaviour is preserved
 - 😞 inserted signals have to be implemented
- **Concurrency reductions – antibiotic**
 - 😊 no new signals
 - 😊 reduced state graph and so more don't-cares in minimisation tables
 - 😞 change the behaviour: need to be careful if input → output (even indirectly) – this puts a new assumption on the environment!
 - 😞 can introduce deadlocks: **Circuit: $a \rightarrow b$ & Environment: $b \rightarrow a$**
- **Timing assumptions – surgery**
 - 😊 no new signals
 - 😊 reduced state graph and so more don't-cares in minimisation tables
 - 😞 break speed-independence
 - 😞 require deep understanding of theory and the circuit's behaviour
 - 😞 introduce layout constraints, and need care & tool support
 - 😞 fragile due to variability (manufacturing, temperature, voltage, etc.)

Online tutorial:
workcraft.org